

# Talon RTR 2742

## Ultra wideband RF/IF rugged rackmount recorder

### Recording system for ultra-wideband analog RF/IF signals

- Sample rates up to 6 GHz
- Record up to 2.4 GHz wide bandwidth signals
- Up to 244 TB of front-panel removable solid state storage
- SystemFlow GUI with Signal Viewer analysis tool



### Talon RTR 2742 is a turn-key record and playback system for

**ultra-wideband analog RF/IF signals.** Using two 12-bit, 6.4 GHz A/D converters, this system can achieve sustained recording of 2.4 GHz bandwidth signals at rates up to 6 GBytes per second. It can be configured as a one- or two-channel system and can record real samples or complex I+Q digitally down-converted samples.

Complemented by a 16-bit, 6.4 GHz D/A converter, the RTR 2742 is capable of playing back analog signal bandwidths up to 1.28 GHz. Built-in digital down- and up-converters provide flexible bandwidth and tuning frequency selection for both record and playback.

The RTR 2742 includes a 12-bit 6.4 GHz A/D that can be clocked at rates from 1.6 to 6 GHz in single-channel mode. Data can be truncated and packed as 8-bit samples, to support continuous recording up to the maximum sample rate. The D/A is capable of reproducing signals with up to 1.28 GHz of instantaneous bandwidth and includes a wide range of interpolations.

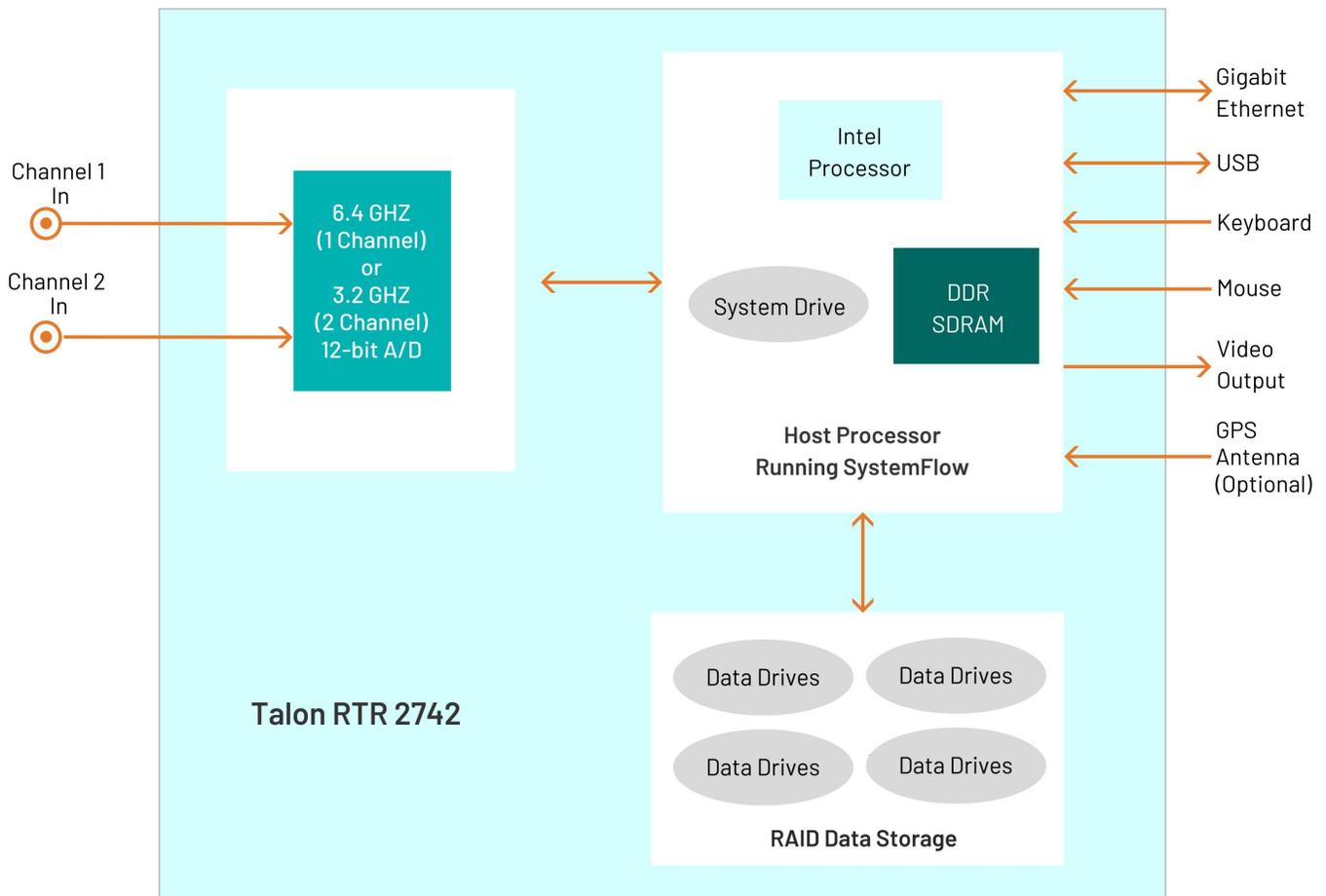
### FEATURES

- Sample rates up to 6 GHz
- Real-time sustained recording rates up to 6 GB/sec
- Integrated DDCs and DUCs
- Record up to 2.4 GHz wide bandwidth signals
- Playback up to 1.28 GHz wide bandwidth signals
- Up to 244 TB of front-panel removable solid state storage
- 4U 19-inch industrial grade server chassis
- SystemFlow GUI with Signal Viewer analysis tool
- C-callable API for integration

**RUGGED AND FLEXIBLE ARCHITECTURE**

The RTR 2742 is configured in a 4U 19-inch rugged rackmount chassis, with hot-swappable data drives, front panel USB ports, and I/O connectors on the rear panel. Systems are scalable to accommodate multiple chassis to increase channel counts and aggregate data rates. All recorder chassis are connected via Ethernet and can be controlled from a single GUI either locally or from a remote PC.

Because SSDs operate reliably under conditions of vibration and shock, the RTR 2742 performs well in ground, shipborne, and airborne environments. The hot-swappable SSDs provide storage capacity of up to 244 TB. The drives can be easily removed or exchanged during or after a mission to retrieve recorded data. RAID levels 0, 5, and 6 provide a choice for the required level of redundancy.



**OPERATIONAL MODES**

The RTR 2742 uses JESD204B A/D and D/A converters that are limited to a set of operational modes. These modes are defined below:

**RECORD MODES**

| Single-Channel Mode                         | Dual-Channel Mode  |
|---|--|
| 8-bit packed real, $f_s = 1600 - 6000$ MHz  | 8-bit packed real, $f_s = 800 - 3000$ MHz                          |
| 16-bit packed real, $f_s = 1600 - 3000$ MHz | 16-bit packed real, $f_s = 800 - 1500$ MHz                         |
|   | 16-bit packed complex DDC, $f_s = 800 - 3000$ MHz (dec = 4)        |
|   | 16-bit packed complex DDC, $f_s = 1300 - 3200$ MHz (dec = 8 or 16) |

**PLAYBACK MODES**

| Single-Channel Mode   | Dual-Channel Mode   |
|---|---|
| 8-bit packed real, $f_s = 1600 - 3200$ MHz                                      | 16-bit packed real, $f_s = 400 - 1250$ MHz                                      |
| 16-bit packed real, $f_s = 400 - 1600$ MHz                                      | 16-bit packed real, $f_s = 800 - 2500$ MHz (int = 2)                            |
| 16-bit packed real, $f_s = 800 - 3200$ MHz (int = 2)                            | 16-bit packed real, $f_s = 1600 - 3200$ MHz (int = 4)                           |
| 16-bit packed real, $f_s = 1600 - 3200$ MHz & 5240 - 6400 MHz (int = 4)         | 16-bit packed complex DUC, $f_s = 1200 - 3200$ MHz (int = 6)                    |
| 16-bit packed complex DUC, $f_s = 800 - 1600$ MHz (int = 2)                     | 16-bit packed complex DUC, $f_s = 1600 - 3200$ MHz (int = 8)                    |
| 16-bit packed complex DUC, $f_s = 1600 - 3200$ MHz (int = 4)                    | 16-bit packed complex DUC, $f_s = 2000 - 3200$ MHz & 5240 - 5750 MHz (int = 10) |
| 16-bit packed complex DUC, $f_s = 1200 - 3200$ MHz (int = 6)                    | 16-bit packed complex DUC, $f_s = 2400 - 3200$ MHz & 5240 - 6400 MHz (int = 12) |
| 16-bit packed complex DUC, $f_s = 1600 - 3200$ MHz & 5240 - 6400 MHz (int = 8)  | 16-bit packed complex DUC, $f_s = 3200$ MHz & 5240 - 6400 MHz (int = 16)        |
| 16-bit packed complex DUC, $f_s = 2000 - 3200$ MHz & 5240 - 6400 MHz (int = 10) | 16-bit packed complex DUC, $f_s = 5240 - 6400$ MHz (int = 18)                   |
| 16-bit packed complex DUC, $f_s = 2400 - 3200$ MHz & 5240 - 6400 MHz (int = 12) | 16-bit packed complex DUC, $f_s = 5240 - 6400$ MHz (int = 24)                   |
| 16-bit packed complex DUC, $f_s = 3200$ MHz & 5240 - 6400 MHz (int = 16)        |   |
| 16-bit packed complex DUC, $f_s = 5240 - 6400$ MHz (int = 18)                   |   |
| 16-bit packed complex DUC, $f_s = 5240 - 6400$ MHz (int = 24)                   |   |

## SYSTEMFLOW SOFTWARE

All Talon recorders include the Mercury SystemFlow<sup>®</sup> recording software. SystemFlow software enables users to configure and control a Talon recorder:

- The SystemFlow GUI provides a point-and-click user interface. It includes Configure, Record, Playback, and Status screens, each with intuitive controls and indicators. The user can easily move between screens to configure parameters, control and monitor a recording, and play back a recorded stream.
- SystemFlow API provides a set of C-callable libraries that allow engineers to develop their own user interface to configure and control their Talon recorder. Additional high-level libraries, like Python, are available upon request.

The SystemFlow GUI and API can be run from a remote connection over Gigabit Ethernet. Recorders can be set up to run autonomously by implementing scripts using the API interface.

Talon systems record all data to the native NTFS file system, allowing for quick and easy access to the data from any computer. A simple header that holds the recording parameters is added to the beginning of each file. An optional GPS receiver allows the user to precisely timestamp files and optionally track the recorder's position throughout a mission.

## SYSTEMFLOW SIMULATOR

To learn more about SystemFlow software, contact Mercury at [techsales@mrcy.com](mailto:techsales@mrcy.com). The SystemFlow Simulator allows you to learn how to use a Talon recorder's SystemFlow software interface before you acquire a recorder or while you are waiting for delivery of a recorder.

The Simulator can simulate the operating environment of all the different Talon recorder models. The Simulator also demonstrates the SystemFlow Signal Viewer by playing recorded signals to simulate the appearance of live signals being digitized and recorded by a Talon analog signal recorder.

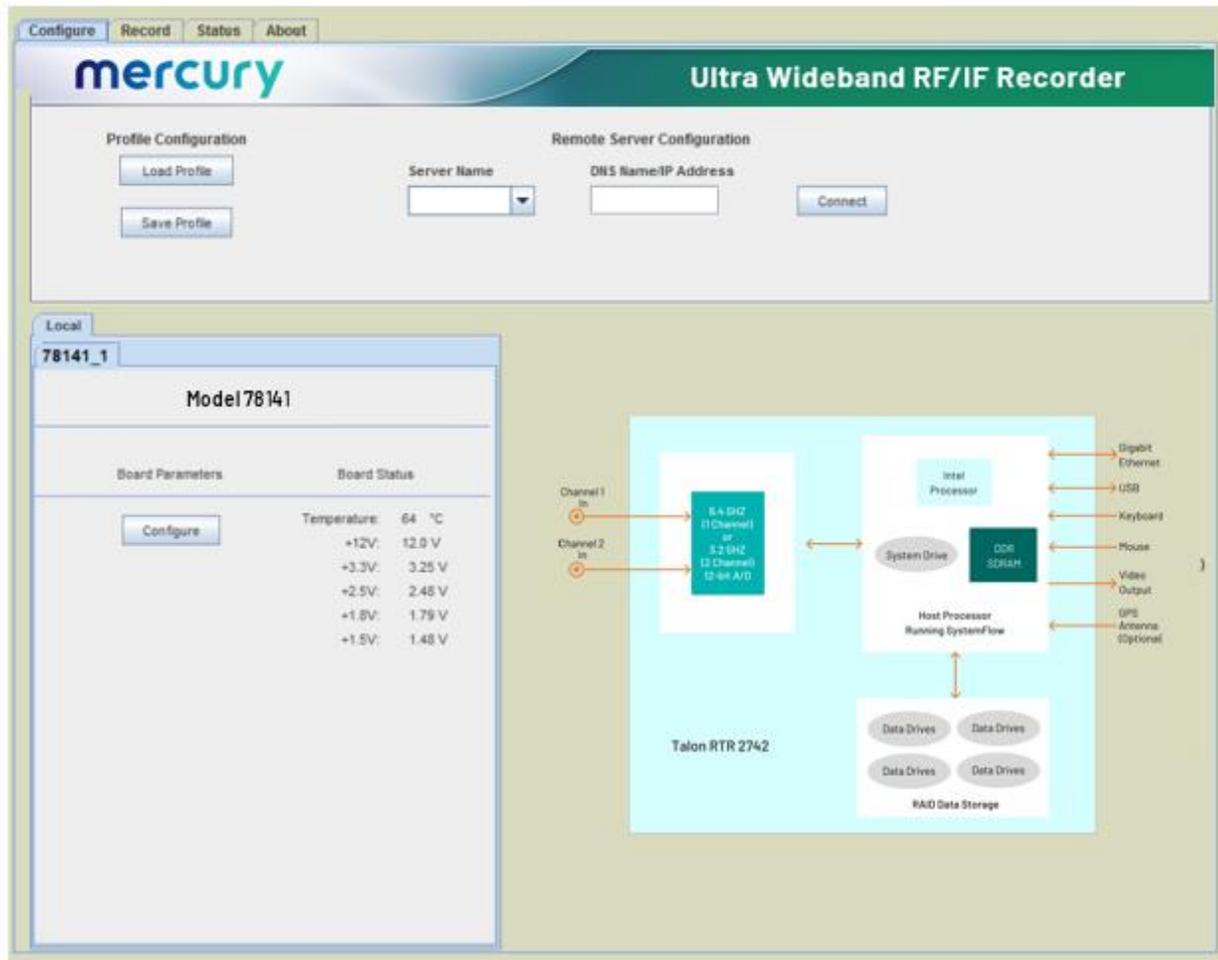
### Features

- Provides real-time recording system simulation
- Allows engineers to write and test their application (built using the SystemFlow API) before receiving the recorder hardware
- Demonstrates SystemFlow signal and file viewer tool
- Capable of simulating all Talon analog and digital recording systems
- Full Talon SystemFlow GUI
- Simulator can be used to develop Talon system profiles for use in the final system

SYSTEMFLOW RECORDER INTERFACE

The RTR 2742 GUI provides the user with a control interface for the recording system. It includes Configuration, Record, Playback and Status screens, each with intuitive controls and indicators. The user can easily move between screens to set configuration parameters,

control and monitor a recording, play back a recorded signal and monitor board temperature and voltage levels. The signal viewer, integrated into the recording GUI, allows the user to monitor real-time signals or signals recorded on disk.



SETTING SYSTEM PARAMETERS

The RTR 2742 configuration GUI provides a simple and intuitive means for setting up the system parameters such as channel mode,

clock frequency, downconversion, and gate/trigger mode. All parameters contain limit-checking and integrated help.

### ADC Input Parameters

|                          |                   |      |
|--------------------------|-------------------|------|
| Channel Mode:            | Single            | MHz  |
| Clock Source:            | Internal          |      |
| Clock Frequency:         | 2800.0            | MHz  |
| Operation Mode:          | 8-bit, real,dec 1 |      |
| Bandwidth:               | 1400.0            | MHz  |
| CH1 Center Frequency:    | 500.0             | MHz  |
| CH2 Center Frequency:    | 500.0             |      |
| Gate / Trigger Mode:     | None              |      |
| Gate / Trigger Polarity: | Positive          |      |
| A/D Sampling Rate:       | 2800.0            | MHz  |
| Disk Data Rate:          | 2800.0            | MS/s |

OK Cancel Apply

### DAC Output Parameters

|                           |                      |      |
|---------------------------|----------------------|------|
| Channel Mode:             | Single               |      |
| Clock Source:             | Internal             |      |
| Clock Frequency:          | 1600.0               | MHz  |
| Operation Mode:           | 8-bit, real,Interp 1 |      |
| Bandwidth:                | 800.0                | MHz  |
| CH1 Center Frequency:     | 500.0                | MHz  |
| CH2 Center Frequency:     | 500.0                |      |
| Gate / Trigger Mode:      | None                 |      |
| Gate / Trigger Polarity:  | Negative             |      |
| D/A Output Sampling Rate: | 1600.0               | MHz  |
| Disk Data Rate:           | 1600.0               | MS/s |

OK Cancel Apply



## SYSTEMFLOW API

SystemFlow includes a complete API (Application Programming Interface) supporting control and status queries of all operations of the Talon recorder from a custom application.

High-level C-language function calls and the supporting device drivers allow users to incorporate the RTR 2742 as a high-performance server front end to a larger system. This is

supported using a socket interface through the Ethernet port, either to a local host or through an internet link for remote, standalone acquisition. Recorded NTFS files can be easily retrieved through the same connection. In addition to C, support is also provided for high level languages such as Python and C#. Below is an example of controlling recording via the SystemFlow API.

```

728     }
729     //transfer until end of disk
730     else if (transferType == TRANSFER_END_OF_DISK)
731     {
732         recordParams->transferTime = 0;           // must set to 0
733         recordParams->transferLength = 0;        // must set to 0
734     }
735
736     //////////////////////////////////////////////////////////////////// Start the record ////////////////////////////////////////////////////////////////////
737     SetConsoleTextAttribute (hConsole, FOREGROUND_GREEN | FOREGROUND_INTENSITY );
738     printf("\nCase 6: RTS_Record\n");
739     SetConsoleTextAttribute (hConsole, wOldColorAttrs);
740
741     //trigger immediately
742     if(recordParams->trigger == RTS_TRIGGER_IMMEDIATELY)
743     {
744         //send record command
745         if ((error = RTS_Record(++msgNum,
746                               serverInfo,
747                               recordParams,
748                               recordChanId,
749                               fileName[0])) != RTS_SUCCESS)
750         {
751             printf("Record Error # 0x%lx.\n", error);
752             exitHandler(error);
753             goto freeMem;
754         }
755
756         Sleep(500);
757     }
758
759     //wait for SW trigger
760     else if(recordParams->trigger == RTS_WAIT_FOR_SW_TRIGGER)
761     {
762         //send record command which set up record and start DMA
763         if ((error = RTS_Record(++msgNum,
764                               serverInfo,
765                               recordParams,
766                               recordChanId,
767                               fileName[0])) != RTS_SUCCESS)

```

**SPECIFICATIONS**

**PC Workstation**

- Operating System: Windows®
- Processor: Intel Core i7 processor (or better)
- SDRAM: (standard) 8 GB
  - Option -309: 16 GB
  - Option -310: 32 GB
  - Option -311: 64 GB

**RAID**

- Storage: 7.6, 15.3, 30.7, 61, 122.8, or 244 TB
- Supported RAID Levels: (standard) 0
  - Option -285: RAID 5
  - Option -286: RAID 6
- Drive Type: SATA III or NVME SSDs

**Analog Signal Inputs**

- Input Type: Two rear panel SSMC connectors, IN 1 & IN 2
- Full Scale Input: +1.0 dBm into 50 ohms
- Maximum Power Input: 12 dBm
- Input Impedance: 50 ohms
- Coupling: Transformer-coupled
- Transformer Type: Marki Microwave BALH-0006SMG
- 3dB Passband: 0.5 MHz to 6000 MHz

**A/D Converters**

- Type: Texas Instruments ADC12DJ3200
- Sampling Rate: Up to 6 GHz
- Resolution: 12 bits
- Anti-Aliasing Filters: External, user-supplied

**Analog Signal Outputs**

- Output Type: Two rear panel SSMC connectors, OUT 1 & OUT 2
- Full Scale Output: +7.5 dBm into 50 ohms
- Output Impedance: 50 ohms
- Coupling: Transformer-coupled
- Transformer Type: Mini-Circuits TCM3-452X-1+
- 3dB Passband: 20 MHz to 4000 MHz

**D/A Converters**

- Type: Texas Instruments DAC38RF82
- Sampling Rate: Up to 6 GHz
- Resolution: 14 bits

**Sampling Clock Source**

Internal fixed-frequency or programmable oscillator (selectable by option); in single-channel mode, the sample rate is 2x the clock frequency; in dual-channel mode, the sample rate equals the clock frequency

**Frequency Reference**

Accepts external 10 MHz reference at 0 to 10 dBm to phase-lock the clock oscillator

**Physical and Environmental**

- 4U Long Chassis: 19" W x 21" D x 7" H
- Weight: 50 lb, approx.
- Operating Temp: 0° to +50° C
- Storage Temp: -40° to +85° C
- Relative Humidity: 5 to 95%, non-condensing
- Operating Shock: 15 g max. (11 msec, half sine wave)
- Operating Vibration: 10 to 20 Hz: 0.02 inch peak, 20 to 500 Hz: 1.4 g peak acceleration
- Power Requirements: 100 to 240 VAC, 50 to 60 Hz, 500 W max.

**ORDERING INFORMATION**

**RAID Configurations**

|             |                      |
|-------------|----------------------|
| Standard    | RAID 0 configuration |
| Option -285 | RAID 5 configuration |
| Option -286 | RAID 6 configuration |

**Memory Options**

|             |                     |
|-------------|---------------------|
| Standard    | 8 GB system memory  |
| Option -309 | 16 GB system memory |
| Option -310 | 32 GB system memory |
| Option -311 | 64 GB system memory |

**Storage Options**

|             |                              |
|-------------|------------------------------|
| Option -415 | 7.6 TB SSD storage capacity  |
| Option -420 | 15.3 TB SSD storage capacity |
| Option -430 | 30.7 TB SSD storage capacity |
| Option -460 | 61.4 TB SSD storage capacity |
| Option -485 | 122.8 TB SSD                 |
| Option -490 | 243.3 TB SSD                 |

| Other Options |                                  |
|---------------|----------------------------------|
| Option -261   | GPS time and position stamping   |
| Option -264   | IRIG-B time stamping             |
| Option -267   | Dual 10 GbE offload              |
| Option -268   | 40 GbE offload                   |
| Option -625   | Removable operating system drive |
| Option -680   | 28V DC power supply              |

Contact Mercury for compatible option combinations.

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Mercury offers worldwide customers shorter development time, reliable, rugged solutions for a variety of environments, reduced costs, and mature software development tools. We offer free lifetime support from our engineering staff, which customers can depend on through phone and email, as well as software updates. Take advantage of our 40 years of experience in delivering high-performance radar, communications, SIGINT, EW, and data acquisition MIL-Aero solutions worldwide.



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