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# **Radar Environment Simulator (RES)**

Modular Design Customizable for Multiple Radar & Seeker Applications

- Modular, configurable & scalable testing platform
- 100s of realistic independent targets per scenario
- Up to 16 simultaneous channels
- Each channel can be programmed as a target, jammer or ECM signature
- Extensive ECM techniques and validated threat library
- SAR scene generation capability

Mercury Systems is the world's largest supplier of DRFM-based and DSP/Synthesizer-based RES systems. These RF Direct Inject simulators have been developed to be generic to support multiple types of radar systems. The Radar Environment Simulator (RES) systems are used for applications ranging from anechoic chamber and open air range (OAR) to laboratory-based radar production testing and comprehensive radar performance evaluation.

To date, Mercury Systems has produced RES systems to test over 50+ different radars and seekers. The RES designs utilize advanced ASIC, FPGA, DSP and DDS technologies for high fidelity signal capture, modulation and regeneration. Coupled with powerful GPGPU processors and OpenVPX standard architecture, the RES systems are very cost-effective and flexible solutions for most radar testing applications.

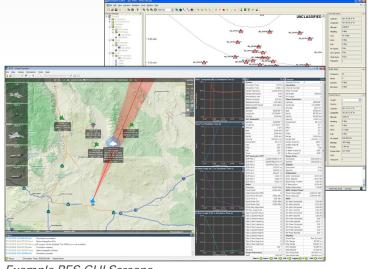
Mercury Systems manufacturers many varieties of RES products based on several different signal processing technologies. This allows Mercury Systems to tailor the best available technology to each customer's requirement

Mercury Systems is a leading commercial provider of secure sensor and safety-critical processing subsystems. Optimized for customer and mission success, Mercury's solutions power a wide variety of critical

defense and intelligence programs.

# Applications

- Air-to-Air & Air-to-Ground radar performance evaluation
- Radar performance evaluation
- ECM vulnerability assessment
- Radar production testing
- ECCM training/tactics development
- Advanced missile seeker/fuse testing
- Air defense personnel training



Example RES GUI Screens



Receiver/processor development

#### Features

- Up to 500 targets per scenario
- Up to 16 simultaneous channels
- Each channel can be a target, ECM, jammingclutter or chaff simulation
- Wide variety of ECM techniques and target modulation, including a validated threat library
- Wide instantaneous dynamic range
- Outputs: Digital, IF and RF baseband to 100GHz
- Closed loop operations with radar
- Real-time external or local host control
- Modular/configurable design
- Standard OpenVPX architecture
- Windows-based Graphical User Interface (GUI)
- Real-time, runtime displays of SUT, targets, ECM, etc.
- Plan, range/bearing and HUD displays available
- High-speed scenario update rate
- High reliability
- Comprehensive BIT and calibration software
- Optional free space interfaces for range and anechoic chamber support
- Optional data link, IFF and video support
- Optional SAR Scene generation capability
- Supports monopulse, multi-channel, multi-beam radars
- Supports mechanical and electronically steered antennas
- Data logging for post-test correlation

## Specifications

#### **Scenario**

Targets in scenario	Up to 500
Targets in beam	Up to 16
Jammers in scenario	Up to 12
Jammers in beam	Up to 4
Chaff in scenario	Up to 12
Chaff in beam	Up to 4
Weather in scenario	Up to 4 cells
Weather in beam	Up to 2

Ground/ship clutter Airborne clutter

Downloadable 360° clutter definition Dynamic MLC, SLC and ALR

SUT dependent-VHF to W-Band

50 ns to CW

<10 Hz to > 5 MHz

Up to <-60 dBc worst case

<65 dBc typical

>120 db

0.25 dB 100 dB

>+5 MHz

<0.1 Hz

<0.3 m

50 m to 1500 km

Mechanical, electronic, combination

OW, pulse, phase-coded, FM (linear and non-linear)

### **Signal Fidelity**

Frequency range
Antenna types
Waveform types
Pulse width
PRI
Spurious
Dynamic range
Dynamic range Amplitude resolution
, 0
Amplitude resolution
Amplitude resolution RF ON/OFF isolation
Amplitude resolution RF ON/OFF isolation Doppler range

# Target Fidelity

Mean RCS value 3-D RCS patterns

Scintillation
Geometry modeling
Jamming assets
Target modulations

0.001 to 1,000 000 m2 ±180° EL, ±90° AZ ±30 dB at 0.25 dB resolution Swerling cases 0-4 + user-defined 6 (DOF) Combination coherent and non-coherent and chaff User-definable modulations for JEM, Blade, etc.; Aspect Angle Dependent

#### **Interface Options**

External computer control Interfaces to additional radars Jammer in the loop interfaces IFF simulation (Mark XII, all modes) IRIG A/B/G for synchronization Free space transmission Man/pilot in the loop Video PPI and data link support Data logging of SUT/target data

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